



To be the global leader as a premium electro-optical systems provider

SKYPATH PODS FAMILY



Pods Series

Micro-series Pods:

SD65D/SD70D/SD70T/
SD80D/SNT100Q



Compact Loitering Munition、 Small Multirotor UAV



Small-series Pods:

SD100T/SD100TP/
SD100TP-10X/SD80DX



Tactical Loitering Munition、 Medium Multirotor UAV、
Fixed-wing/Compound-wing UAV



Medium-series Pods:

SD130D/SD130T/SD130TP
/SD155T/SD170T



Strategic Loitering Munition、 Large Multirotor UAV、
Medium-Large Fixed-wing/Compound-wing UAV



EO/IR Pod Development & Manufacturing Facility



Micro-series 2/3-axis Pods

250g-400g Series

This series of pods weighs between 250g to 400g, with diameter options ranging from 65mm to 100mm. Featuring configurable EO/IR/LRF payloads, they provide onboard capabilities including image acquisition, manual interception, auto-tracking, and manual tracking. The three-axis high-stability platform framework integrates recognition, tracking, inertial stabilization, and lock-on functions, delivering professional and reliable operational support for industrial drones in inspection, security surveillance, emergency rescue, and search missions.

Key Features

- **Panoramic Vision, Target Insight**

Equipped with various EO/IR/LRF payloads, providing 24/7 stable and clear imaging

- **Omnidirectional Reliability**

High-precision inertial stabilized platform enables 360° continuous obstruction-free rotation

- **Automatic Target Recognition & Tracking**

Standard target auto-identification; dual-optical tracking with real-time video transmission of tracking frame data

- **Military-Grade Environmental Adaptability**

Military alloy components, industrial-grade devices, compatible with various harsh industrial application environments

- **Compact Size, Light Weight, High Performance**

Precision opto-mechatronic integrated design, smaller, lighter, and more powerful than same-category products

- **Rich Interfaces, Strong Compatibility**

Communication supports RS422, RS232, S.BUS networks and Mavlink protocol; video supports synchronized 422 and network transmission

SD65D (65mm 2-axis/EO/IR)



System Parameters

Dimensions: 65×72×88mm

Weight: ≤240g

Voltage : 18V~32VDC

Consumption: Stable Power Consumption ≤20W ,

Peak Power Consumption ≤40W

Working temperature: -40°C ~55°C

Servo Platform

Rotation range: Pan: -110° ~+110°

Tilt: -85° ~+25°

Angular position accuracy: ≤0.3°

Stabilization accuracy: ≤0.1mrad

Maximum angular velocity: Azimuth≥20°/s ,

Pitch≥20°/s

Visible light camera

Resolution: 1920×1080

Lens: 12mm

FOV: 26°×15°

Detection range: 1.5km

Recognition range: 1.0km

Infrared thermal imager

Resolution : 640×512

Lens: 19mm

Pixel size: 12μm

FOV: 23°×18°

Detection range : 1.0km

Recognition range : 0.5km

SD70D (70mm 2-axis/EO/IR)



System Parameters

Dimensions : 70×73×92.2mm

Weight : ≤250g

Voltage: 14V~28VDC

Consumption: Stable Power Consumption

≤12W, Peak Power Consumption ≤20W

Working temperature : -40°C ~55°C

Servo Platform

Rotation range: Pan : -90° ~+90°

Tilt : -90° ~+30°

Angular position accuracy: ≤0.3°

Stabilization accuracy: ≤0.1mrad

Maximum angular velocity: Azimuth≥50°/s,

Pitch≥50°/s

Visible light camera

Resolution : 2560×1440

Lens : 16mm

FOV : 26.1°×14.9°

Detection range : People2.5km/Vehicle9.5km

Recognition range :

People0.32km/Vehicle1.2km

Infrared thermal imager

Resolution : 640×512

Lens: 25mm

Pixel size : 12μm

FOV: 17.5°×13.1°

Detection range : People1km/Vehicle2.4km

Recognition range : People0.33km/Vehicle0.8km

SD70T (70mm 2-axis/EO/IR/WA-EO)



System Parameters

Dimensions : 70×73×93mm

Weight : ≤250g

Voltage : 12V~32VDC

Consumption: Stable Power Consumption

≤12W, Peak Power Consumption ≤20W

Working temperature : -20°C ~55°C

Servo Platform

Rotation range: Pan : -90° ~+90°

Tilt : -90° ~+30°

Angular position accuracy: ≤0.3°

Stabilization accuracy: ≤0.1mrad

Maximum angular velocity: Azimuth≥50°/s,

Pitch≥50°/s

Visible light camera

Resolution : 2560×1440

Lens : 16mm

FOV: 26.1°×14.9°

Detection range : People2.5km/Vehicle9.5km

Recognition range : People0.32km/Vehicle1.2km

Infrared thermal imager

Resolution : 640×512

Lens: 25mm

Pixel size : 12μm

FOV: 17.5°×13.1°

Detection range : People1km/Vehicle2.4km

Recognition range : People0.33km/Vehicle0.8km

Wide-angle Visible light camera

Resolution : 2560×1440

Lens: 4.45mm

FOV: 79.7°×50.3°

SD80D (80mm 2-axis/EO/IR)



System Parameters

Dimensions : 80×86×110mm

Weight : ≤360g

Voltage : 18V~32VDC

Consumption: Stable Power Consumption
≤20W, Peak Power Consumption ≤60W

Working temperature : -40°C ~55°C

Servo Platform

Rotation range: Pan: -110° ~+110°

Tilt: -85° ~+25°

Angular position accuracy: ≤0.3°

Stabilization accuracy: ≤0.1mrad

Maximum angular velocity: Azimuth≥20°/s,

Pitch≥20°/s

Visible light camera

Resolution : 3840×2160

Lens: 16mm

FOV: 26°×15°

Detection range : 2.0km

Recognition range : 1.0km

Infrared thermal imager

Resolution : 640×512

Lens: 19mm

Pixel size : 12μm

FOV: 17.4°×14°

Detection range : 1.3km

Recognition range : 0.7km

SNT100Q (100mm 3-axis/EO/IR/LRF/WA-EO)



System Parameters

Dimensions : 90×105×124mm

Weight : ≤380g

Voltage : 12VDC

Consumption: Stable Power Consumption

≤12W , Peak current ≤10A

Working temperature : -20°C ~55°C

Servo Platform

Rotation range: Pan : 360°×n (360° rotation)

Tilt : -130° ~+90°

Roll: -60° ~+60°

Angular position accuracy: ≤0.3°

Stabilization accuracy: ≤0.1mrad

Maximum angular velocity: Azimuth≥60°/s, Pitch≥60°/s

Visible light camera

Resolution : 4800W

Lens: 15~50mm

FOV: 29°×23.5°~9°×7°

Detection range :

People0.7km/Vehicle2.6km

Recognition range :

People90m/Vehicle0.34km

Infrared thermal imager

Resolution : 640×512

Lens : 19mm

Pixel size : 12μm

FOV: 22.8°×18.4°

Detection range : People1km/Vehicle2.4km

Recognition range : People0.33km/Vehicle0.8km

Laser rangefinder

Ranging accuracy: 5m~1.2km

Ranging accuracy: ≤1m

Ranging frequency: 1Hz

Wide-angle Visible light camera

Resolution : 4800W

Lens : 4.49mm

FOV: 83°×53°

Small-series 2/3-axis Pods

500g-1kg Series

This series of pods weighs between 500g to 1kg, with diameter options ranging from 80mm to 100mm. Featuring configurable EO/IR/LRF payloads, they provide onboard capabilities including image acquisition, manual interception, auto-tracking, and manual tracking. The three-axis high-stability platform framework integrates recognition, tracking, inertial stabilization, and lock-on functions, delivering professional and reliable operational support for industrial drones in inspection, security surveillance, emergency rescue, and search missions.

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Standard target auto-identification; dual-optical tracking with real-time video transmission of tracking frame data

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SD100T (100mm 2-axis/EO/IR/LRF)



System Parameters

Dimensions : 105×91.4×148.4mm

Weight : ≤600g

Voltage : 12V~32VDC

Consumption: Stable Power Consumption

≤30W , Peak current ≤5A

Working temperature : -40°C ~55°C

Servo Platform

Rotation range: Pan : 360°×n (360° rotation)

Tilt: -110° ~+45°

Roll: -40° ~+40°

Angular position accuracy: ≤0.3°

Stabilization accuracy: ≤0.1mrad

Maximum angular velocity: Azimuth≥50°/s, Pitch≥50°/s

Visible light camera

Resolution : 1920×1080

Lens : 4.8~48mm

FOV : 60.2°×33.9°

Detection range : People7.6km/Vehicle28km

Recognition range : People0.95km/Vehicle3.5km

Infrared thermal imager

Resolution : 640×512

Lens : 25mm

Pixel size : 12μm

FOV : 17.5°×13.1°

Detection range : People1km/Vehicle2.4km

Recognition range : People0.33km/Vehicle2.8km

Laser rangefinder

Ranging accuracy: 5m~1.2km

Ranging accuracy: ≤1m

Ranging frequency: 1Hz

SD100TP (100mm 2-axis/EO/IR/LRF)



System Parameters

Dimensions : 100×100×135mm

Weight : ≤650g

Voltage : 18V~32VDC

Consumption: Stable Power Consumption
≤20W, Peak Power Consumption ≤70W

Working temperature : -40°C ~55°C

Servo Platform

Rotation range: Pan: -110° ~+110°

Tilt: -85° ~+20°

Angular position accuracy: ≤0.3°

Stabilization accuracy: ≤0.1mrad

Maximum angular velocity: Azimuth≥20°/s,

Pitch≥20°/s

Visible light camera

Resolution : 3840×2160

Lens : 16mm

FOV: 26°×15°

Detection range : 3.0km

Recognition range : 1.5km

Infrared thermal imager

Resolution : 640×512

Lens : 25mm

Pixel size : 12μm

FOV: 10.7°×8.5°

Detection range : 1.5km

Recognition range : 1.0km

Laser rangefinder

Ranging accuracy: 5m~1.5km

Ranging accuracy: ≤2m

Ranging frequency: 1Hz

SD100TP-10X (100mm 3-axis/EO/IR/LRF)



System Parameters

Dimensions : 100×132×148mm

Weight : ≤720g

Voltage : 12V~32VDC

Consumption: Stable Power Consumption

≤30W , Peak current ≤5A

Working temperature : -20°C ~60°C

Servo Platform

Rotation range: Pan : 360°×n (360° rotation)

Tilt: -110° ~+35°

Roll: -50° ~+50°

Angular position accuracy: ≤0.3°

Stabilization accuracy: ≤0.2mrad

Maximum angular velocity: Azimuth≥50°/s, Pitch≥50°/s

Visible light camera

Resolution : 1920×1080

Lens : 5~50mm

FOV : 54°~4.9°

Zoom: 10X optical + 32X digital

Detection range : 3.0km

Recognition range : 1.5km

Infrared thermal imager

Resolution : 640×512

Lens : 25mm

Pixel size : 12μm

FOV : 17°×14°

Detection range : 1.5km

Recognition range : 1.0km

Laser rangefinder

Ranging accuracy: 5m~2km

Ranging accuracy: ≤2m

Ranging frequency: 1Hz

SD80DX (80mm Horizontal/EO/IR)



System Parameters

Dimensions : $\phi 80 \times 107 \text{mm}$

Weight : $\leq 450 \text{g}$

Voltage : 18V~32VDC

Consumption: Stable Power Consumption
 $\leq 20 \text{W}$, Peak Power Consumption $\leq 60 \text{W}$

Working temperature : $-40^{\circ}\text{C} \sim 55^{\circ}\text{C}$

Servo Platform

Rotation range: Pan : $-90^{\circ} \sim +90^{\circ}$

Tilt: $-90^{\circ} \sim +20^{\circ}$

Angular position accuracy: $\leq 0.3^{\circ}$

Stabilization accuracy: $\leq 0.1 \text{mrad}$

Maximum angular velocity: Azimuth $\geq 20^{\circ}/\text{s}$,

Pitch $\geq 20^{\circ}/\text{s}$

Visible light camera

Resolution : 3840×2160

Lens : 16mm

FOV : $26^{\circ} \times 15^{\circ}$

Detection range : 2.0km

Recognition range : 1.0km

Infrared thermal imager

Resolution : 640×512

Lens : 25mm

Pixel size : $12 \mu\text{m}$

FOV : $23^{\circ} \times 18^{\circ}$

Detection range : 1.3km

Recognition range : 0.6km

Medium-series 2/3-axis Pods

≥1kg Series

This series of pods weighs > 1kg, with diameter options ranging from 130mm to 170mm. Featuring configurable EO/IR/LRF payloads, they provide onboard capabilities including image acquisition, manual interception, auto-tracking, and manual tracking. The three-axis high-stability platform framework integrates recognition, tracking, inertial stabilization, and lock-on functions, delivering professional and reliable operational support for industrial drones in inspection, security surveillance, emergency rescue, and search missions.

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SD130D (130mm 2-axis/EO/IR)



System Parameters

Dimensions : 130×153×212mm

Weight : ≤1kg

Voltage : 12V~32VDC

Consumption: Stable Power Consumption

≤30W , Peak current ≤5A

Working temperature : -20°C ~55°C

Servo Platform

Rotation range: Pan : 360°×n (360° rotation)

Tilt: -125° ~+90°

Angular position accuracy: ≤0.3°

Stabilization accuracy: ≤0.1mrad

Maximum angular velocity: Azimuth≥20°/s,

Pitch≥20°/s

Visible light camera

Resolution : 1920×1080

Lens : 4.8~158mm

FOV : 58.9°×33.1°

Detection range : People25km/Vehicle94km

Recognition range : People3km/Vehicle11km

Infrared thermal imager

Resolution : 640×512

Lens : 35mm

Pixel size : 12μm

FOV : 12.5°×10°

Detection range : People1.4km/Vehicle3.3km

Recognition range : People0.46km/Vehicle1.1km

SD130T (130mm 2-axis/EO/IR/LRF)



System Parameters

Dimensions : 130×153×212mm

Weight : ≤1.1kg

Voltage : 12V~32VDC

Consumption: Stable Power Consumption

≤30W , Peak current ≤5A

Working temperature : -20°C ~55°C

Servo Platform

Rotation range: Pan : 360°×n (360° rotation)

Tilt: -110° ~+90°

Roll: -40° ~+40°

Angular position accuracy: ≤0.3°

Stabilization accuracy: ≤0.2mrad

Maximum angular velocity: Azimuth≥50°/s, Pitch≥50°/s

Visible light camera

Resolution : 1920×1080

Lens : 4.8~158mm

FOV : 58.9°×33.1°

Detection range : People25km/Vehicle94km

Recognition range : People3km/Vehicle 11km

Infrared thermal imager

Resolution : 640×512

Lens : 35mm

Pixel size : 12μm

FOV : 12.5°×10°

Detection range : People1.4km/Vehicle3.3km

Recognition range : People0.46km/Vehicle1.1km

Laser rangefinder

Ranging accuracy: 20m~3km

Ranging accuracy: ≤2m

Ranging frequency: 1Hz

SD130TP (130mm 3-axis/EO/IR/LRF)



System Parameters

Dimensions : $\phi 130 \times 190 \text{mm}$

Weight : $\leq 1.2 \text{kg}$

Voltage : 18V~32VDC

Consumption: Stable Power Consumption

$\leq 30 \text{W}$, Peak current $\leq 5 \text{A}$

Working temperature : $-20^{\circ}\text{C} \sim 55^{\circ}\text{C}$

Servo Platform

Rotation range: Pan : $360^{\circ} \times n$ (360° rotation)

Tilt: $-115^{\circ} \sim +90^{\circ}$

Roll: $-40^{\circ} \sim +40^{\circ}$

Angular position accuracy: $\leq 0.3^{\circ}$

Stabilization accuracy: $\leq 0.1 \text{mrad}$

Maximum angular velocity: Azimuth $\geq 50^{\circ}/\text{s}$, Pitch $\geq 50^{\circ}/\text{s}$

Visible light camera

Resolution : 1920×1080

Lens : 4.3~129mm

FOV : $63.7^{\circ} \times 35.8^{\circ}$

Zoom: 30X optical + 4X digital

Detection range : People 3km/Vehicle 9km

Recognition range : People 1.5km/Vehicle 4.7km

Infrared thermal imager

Resolution : 640×512

Lens : 40mm

Pixel size : $12 \mu\text{m}$

FOV : $10^{\circ} \times 8^{\circ}$

Detection range : People 0.5km/Vehicle 1.3km

Recognition range : People 0.18km/Vehicle 1km

Laser rangefinder

Ranging accuracy: 5m ~ 1.5km

Ranging accuracy: $\leq 2 \text{m}$

Ranging frequency: 1 ~ 10Hz

SD155T (155mm 2-axis/EO/IR/LRF)



System Parameters

Dimensions : 155×165×208mm

Weight : ≤2kg

Voltage : 20V~32VDC

Consumption: Stable Power Consumption

≤30W , Peak current ≤5A

Working temperature : -20°C ~60°C

Servo Platform

Rotation range: Pan : 360°×n (360° rotation)

Tilt: -115° ~+90°

Angular position accuracy: ≤0.2°

Stabilization accuracy: ≤0.1mrad

Maximum angular velocity: Azimuth≥60°/s,

Pitch≥60°/s

Visible light camera

Resolution : 1920×1080

Lens : 4.3~129mm

FOV : 63.7°×35.8°

Detection range : People20km/Vehicle25km

Recognition range : People2.5km/Vehicle6.4km

Infrared thermal imager

Resolution : 640×512

Lens : 60mm

Pixel size : 12μm

FOV : 7.32°×5.86°

Detection range : People2.4km/Vehicle5.7km

Recognition range : People0.8km/Vehicle1.9km

Laser rangefinder

Ranging accuracy: 20m ~ 3km

Ranging accuracy: ≤2m

Ranging frequency: 1 ~ 5Hz

SD170T (170mm 2-axis/EO/IR/LRF)



System Parameters

Dimensions : $\phi 170 \times 221 \text{mm}$

Weight : $\leq 2.55 \text{kg}$

Voltage : 20V~28VDC

Consumption: Stable Power Consumption

$\leq 20 \text{W}$, Peak Power Consumption $\leq 90 \text{W}$

Working temperature : $-20^{\circ}\text{C} \sim 55^{\circ}\text{C}$

Servo Platform

Rotation range: Pan : $360^{\circ} \times n$ (360° rotation)

Tilt: $-110^{\circ} \sim +10^{\circ}$

Angular position accuracy: $\leq 0.3^{\circ}$

Stabilization accuracy: $\leq 0.1 \text{mrad}$

Maximum angular velocity: Azimuth $\geq 60^{\circ}/\text{s}$,

Pitch $\geq 60^{\circ}/\text{s}$

Visible light camera

Resolution : 1920×1080

Lens : 4.9~147mm

Zoom: 30X optical

Detection range : People 6km/Vehicle 15km

Recognition range : People 2km/Vehicle 8km

Infrared thermal imager

Resolution : 640×512

Lens : 63mm

Pixel size : $12 \mu\text{m}$

FOV : $6.9^{\circ} \times 5.5^{\circ}$

Detection range : People 1.4km/Vehicle 8.4km

Recognition range : People 0.35km/Vehicle 2.1km

Laser rangefinder

Ranging accuracy: 5km

Ranging accuracy: $\leq 2 \text{m}$

Ranging frequency: 1Hz

THANK YOU